**Conversion of a Music Macro Language Variant to MIDI**

**Analysis**

**Background to Problem**

The MIDI file format is a widespread and established standard for storing music. The music macro language (MML) is a niche language for describing music in a comparable way to how music is stored in MIDI files. It has no real standards, but has evolved over the years into different versions, the use of which are provided by BASIC implementations. One of the key issues with the MML is how there is not much software available that can play it; another issue is that the MML is, by design, only suited for monophonic tracks.

This project seeks to tackle both of these issues by providing a facility that can convert a number of files containing a music description language similar to MML into a single multi-channel MIDI file. This allows the benefits of both the MML and MIDI formats to be taken advantage of – music is easily entered with MML, and it is easily playable using the MIDI format.

**Research Methods**

**The MIDI Specification**

The first thing I have researched for this project is the specification of MIDI files.

Values in MIDI files are either stored as big endian binary numbers or as big endian variable length quantities.

MIDI files are composed of “chunks”, which all consist of, at least, a 4-byte string, identifying the type of chunk, and the length of the chunk as a 32-bit integer. There are two different types of chunks featured in the MIDI specification 1.1 – header chunks and track chunks.

The following table shows how headers chunks are structured:

|  |  |  |  |
| --- | --- | --- | --- |
| Bits 0-7 | Bits 8-15 | Bits 16-23 | Bits 24-31 |
| The ASCII characters “MThd” | | | |
| Length | | | |
| Format | | Ntrks | |
| Division | |

“Length” is a 32-bit unsigned integer describing how many bytes are left of the chunk. It is always 6 for a header chunk.

“Format” is a 16-bit unsigned integer that describes the format of the MIDI file. It can currently take three values:

|  |  |
| --- | --- |
| Format | Description |
| 0 | The MIDI file is composed of a header chunk and a single track chunk |
| 1 | The MIDI file is composed of a header chunk  and multiple track chunks that are to be played simultaneously |
| 2 | The MIDI file is composed of a header chunk  and multiple track chunks that are to be played independently |

“Ntrks” is a 16-bit unsigned integer that indicates how many track chunks there are in the file.

“Division” is a 16-bit unsigned integer that sets the meaning of the delta-times (which are variable length quantities put before every event, representing how long should be left from the end of the last event to the beginning of the current one).

The next table shows how track chunks are structured:

|  |  |  |  |
| --- | --- | --- | --- |
| Bits 0-7 | Bits 8-15 | Bits 16-23 | Bits 24-31 |
| The ASCII characters “MTrk” | | | |
| Length | | | |
| MTrk Events ... | | | |

“Length”, like in the header chunk, is a 32-bit unsigned integer describing how many remaining bytes there are to be read in the chunk.

The rest of the track chunk consists of MTrk events, which are structured as follows:

<MTrk event> = <delta time> <event>

“Delta time” is a variable length quantity that represents the length of time to leave between this event and the last one.

“Event” can be one of three different varieties: MIDI, sysex and meta.

MIDI events are MIDI channel messages, such as note down and note up.

Sysex (system exclusive) events are messages that are sent via the MIDI file, but are not related to the playing of it.

Meta events describe how the MIDI commands should be played, and give supplementary information about the track, such as its name and cues.

The MIDI events that will be relevant for the project are shown in the table below: “nnnn” is where the nibble representing the channel number the message is for is placed.

|  |  |  |
| --- | --- | --- |
| Status Byte | Data Bytes | Description |
| 1000 nnnn | 0kkkkkkk | Note off event – sent when a key is released.  0kkkkkkk is the note number.  0vvvvvvv is the velocity. |
| 0vvvvvvv |
| 1001 nnnn | 0kkkkkkk | Note on event – sent when a key is depressed.  0kkkkkkk is the note number.  0vvvvvvv is the velocity. |
| 0vvvvvvv |
| 1100 nnnn | 0ppppppp | Patch change – sent when the instrument is changed.  0ppppppp is the new patch number. |

The meta events that will be used in the project are shown below.

|  |  |
| --- | --- |
| Form (hex) | Description |
| FF 03 [length] [name] | Track name – this command contains the name of the track.  [length] is the length of the name following, as a variable length quantity.  [name] is an ASCII string. |
| FF 2F 00 | End of track – always present at the end of track chunk. |
| FF 51 03 tttttt | Set tempo.  “tttttt” is three bytes that represent the number of microseconds per MIDI crochet. |
| FF 58 04 nn dd cc bb | Time signature.  “nn” is a byte representing the top of a traditional time signature.  “dd” is a byte representing the bottom of a traditional time signature as .  “cc” is a byte setting the number of MIDI clocks per metronome tick.  “bb” is a byte setting the number of demisemiquavers per 24 MIDI clocks (usually 8) |

A full example of a MIDI file in hexadecimal is shown below, split up into a table with descriptions on each section.

|  |  |
| --- | --- |
| 4D 54 68 64 | “MThd” |
| 00 00 00 06 | Length of header chunk |
| 00 00 | Format 0 |
| 00 01 | One track |
| 00 20 | 32 ticks per crochet |
| 4D 54 72 6B | “MTrk” |
| 00 00 00 2A | Length of track chunk |
| 00 FF 58 04 04 02 18 08 | Set time signature to 4/4.  Set 24 MIDI clocks per metronome tick.  Set 8 demisemiquavers per 24 MIDI clocks |
| 00 FF 51 03 07 A1 20 | Set tempo to 0x07A120 (500 000) microseconds per 24 MIDI clocks. This corresponds to 120 BPM in this context. |
| 00 C0 30 | Set channel 0 to patch number 48 |
| 00 C1 30 | Set channel 1 to patch number 48 |
| 00 90 45 7F | Play note with MIDI number 69 (A4) on channel 0 with maximum velocity. |
| 81 10 80 45 7F | Release note with MIDI number 69 (A4) on channel 1 with maximum velocity after a delta time of 0x90. |
| 00 91 40 7F | Play note with MIDI number 64 (E4) on channel 1 with maximum velocity. |
| 7F 80 40 7F | Release note with MIDI number 64 (E4) on channel 1 with maximum velocity after a delta time of 0x7F. |
| 00 FF 2F 00 | End of track |

**Development Tools and Method**

There are many programming languages that would be suitable for this project, but I have chosen to go with C, as I am comfortable with it, and I feel that it is suitable, being a low-level language and the amount of byte-wise manipulation needed in this project.

Python would also have been a good choice because of how easy string manipulation is in it, which would make the processing of the input language more convenient.

I found two tools in my research that I have decided to use in this project to produce the parsing portions of the code – Lex and Yacc. Lex takes a C file containing regular expressions and code to execute upon matches, and Yacc, which works in conjunction with Lex, takes a C file containing Back-Naur form grammar and code to execute upon reductions.

To learn how to use Lex and Yacc, I’ve purchased an O’Reilly book on them, which I’ll be using throughout the project.

An alternative to using Lex and Yacc would be writing my own parser and lexer, which could potentially yield faster code, but would take a great deal longer to develop.

To compile my code, I will use makefiles in combination with GCC. This is a common practice for C development, and one I am comfortable with. The alternative is entering the GCC, Lex and Yacc calls every time compilation is performed, which could be very inconvenient.

Clang is another C compiler that could be used, which has many advantages over GCC, such as compilation speed, but I am used to using GCC and have it already available on the machines I will be developing the project on.

**Description of the Current System**

The current way to convert multiple music macro language like files into a single multi-channel MIDI file is to step through by hand and enter the information as if writing a new MIDI file. This is tedious, unreliable and slow.

**Identification of Potential Users**

There is a small, but dedicated, remaining group of musicians that still use the music macro language

**Identification of User Need and Limitations**

Users will need to be able to use all of the syntax of the MML, as it would be difficult to enter music if even one feature was removed.

The users should not need to have any technical knowledge to use the solution.

The solution should be fast enough to keep up with a musicians work flow, otherwise this would be stifling for their creativity.

The syntax of the MML used by the solution should be at least similar to what already exists, so as to minimise the effort required by the user.

**Data Flow Diagrams**

The following flow chart shows how the solution to the problem should work in terms of file flow:

**F:\School work\A Level\Computer Science\MML-To-Midi-Project\Project Documentation\Diagrams\Analysis_Data_Flow.png**

**Use Cases**

A musician whom uses the MML to compose music would likely find the tools written for this project very useful, as it allows the conversion of their preferred format to an easily playable and portable form.

The solution would also very suitable for a less musically experienced individual, as it is easy to alter and enter music in MML, in contrast to traditional sheet music.

**Potential Solutions**

One solution to the problem is to have one terminal program that the user enters the paths to the input MML files into, and have it output the desired MIDI file. There are a number of pros and cons in this potential solution:

|  |  |
| --- | --- |
| Single Program Advantages | Single Program Disadvantages |
| Easy to use | The program would be complex, given what functionality it must have |

Another solution would be to have two programs that are designed to be used in conjunction: the first would take a single MML file and output a single-channel MIDI file, and the second would take multiple single-channel MIDI files and output a single multiple-channel MIDI file. Some advantages and disadvantages to this approach are shown below:

|  |  |
| --- | --- |
| Program Pair Advantages | Program Pair Disadvantages |
| Each program would be more simple to write, compared to a single complex program | More difficult for to use |
| Each channel of the final MIDI file can be listened to, as a single-channel MIDI file of it would be generated before-hand |  |

**Chosen Solution**

I have chosen to use the solution featuring a pair of programs. This is primarily because I feel that the complexity of both programs combined would be less than the complexity of one larger program.

**Objectives of the Project**

* A program should be written that takes text file containing a variant of the MML as an input, and outputs a single-channel MIDI file that can be play with conventional software.
* A program should be written that takes multiple MIDI files generated by the aforementioned program and combines them into a single multi-channel MIDI file. This combined MIDI file should be playable using conventional software also.
* The programs written for this project should:
  + Complete their execution in under one second, so as to not interrupt the users work flow
  + Use less than half a megabyte of memory during execution
  + Be a less than a quarter of a megabyte in size
* A version of the music macro language should be designed that will be used as the input for the program that generates a single-channel MIDI file from a single MML file. This language should:
  + Have all the functionality of existing variants of the MML, including support for:
    - Octave changing
    - Accidentals
    - Default length setting
    - Volume changing
    - Tempo setting
    - Macros
  + Have as unambiguous a syntax as possible, with a clear logical progression

**Documented Design**

**Target Hardware**

The programs are will be written for Unix based operating systems such as OS X and Linux, as this is what I will be developing them on and am used to working with these systems. Also, the programs will be written to run on little endian processors – this is relevant because the endianness of many numbers will be flipped in the programs.

**Overall System Design**

The following tables are IPSO charts for the mmltomidi and catmidi programs respectively:

|  |  |  |  |
| --- | --- | --- | --- |
| Inputs | Processes | Storage | Outputs |
| MML text file | MML text | Single-channel MIDI file | Success message |

|  |  |  |  |
| --- | --- | --- | --- |
| Inputs | Processes | Storage | Outputs |
| Single-channel MIDI files | MIDI file contents | Multi-channel MIDI file | Success message |

**mmltomidi – User Interface**

The mmltomidi program will be called via the terminal with the form shown below:

mmltomidi [-o output\_path] mml\_file

The “-o” switch sets the output file to be the “output\_path” following. If the switch is not present, then the output file will be called “output.midi” and placed in the working directory. The “mml\_file” portion is where the path to the input file is put.

**catmidi – User Interface**

The catmidi program will be called, similarly to mmltomidi, via the terminal with the form shown below:

catmidi [-o output\_path] [path ...]

The “-o” switch will function exactly as described in the mmltomidi user interface section. “[path ...]” is where the paths to the input MIDI files are put, delimited by spaces

**mmltomidi – Procedural Abstraction**

The following is a flow chart showing a broad abstraction of how the mmltomidi program will work:

F:\School work\A Level\Computer Science\MML-To-Midi-Project\Project Documentation\Diagrams\mmltomidi_procedural_abstraction.png

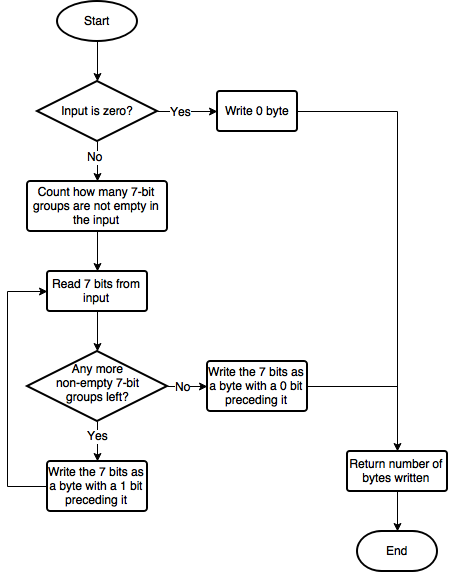
**mmltomidi – Key Algorithms**

**Variable Length Quantity Writing**

One of the most utilised algorithms will be to write a variable length quantity. It will take as inputs a pointer to where the data should be written, and the number that should be written as a variable length quantity. It will return the length of the data written. A list of inputs and expected outputs in hexadecimal for this algorithm are shown below.

|  |  |  |
| --- | --- | --- |
| Input Number | Data Written | Length of Data Written |
| 00 00 00 00 | 00 | 1 |
| 00 00 00 7F | 7F | 1 |
| 00 00 00 80 | 81 00 | 2 |
| 00 00 3F FF | FF 7F | 2 |
| 00 00 40 00 | 81 80 00 | 3 |
| 0F FF FF FF | FF FF FF 7F | 4 |

A flow chart showing a procedural abstraction of the algorithm is below.



**Endianness Swapper**

An endianness swapper is another algorithm that will be commonly used throughout the mmltomidi program. It will take a binary number as an input, and output the same binary number, but with it’s endian swapped. The table below shows what outputs would be given for example inputs.

|  |  |
| --- | --- |
| Input Binary Number | Output Binary Number |
| 00 00 00 00 | 00 00 00 00 |
| 00 00 00 FF | FF 00 00 00 |
| 00 FF 00 00 | 00 00 FF 00 |
| 12 34 56 78 | 78 56 34 12 |

A C-like pseudo-code implementation of this algorithm is shown below.

|  |
| --- |
| int swapIntEndian(int input) {  int output = 0;  for each byte in input {  write the byte to the byte of opposite significance in output  }  return output  } |

**MIDI Data from Processed MML Commands**

The key algorithm of the program, however, is that which generates the MIDI data from the processed MML text data. The flowchart below demonstrates how it will function.

F:\School work\A Level\Computer Science\MML-To-Midi-Project\Project Documentation\Diagrams\generate_midi_file.png

**mmltomidi – Main Data Structures**

The following chunk of code represents the key data structures that store the MML data found by the parser for the MIDI data-generating program.

struct note {

char command; //Letter

char accidental; //-1 for flat, 1 for sharp

unsigned char modifier; //Number after

};

struct mmlFileStruct {

char name[256]; //Null terminated

struct note notes[16384];

int noteCount;

};

The main structure is “mmlFileStruct”. This contains the name of the track, the number of notes in the track, and a list of every note and command in the program. The “note” structure is used only to represent a note or command in the “mmlFileStruct” structure. It contains the letter representing the command, whether a note is an accidental or not, and the modifying number for the command.

Below is an example assignment of these data structures.

|  |
| --- |
| struct mmlFileStruct exampleMMLFileStruct;  strcpy(exampleMMLFileStruct.name, “Test track”);  exampleMMLFileStruct.notes[0].command = ‘a’;  exampleMMLFileStruct.notes[0].accidental = 0;  exampleMMLFileStruct.notes[0].modifier = 5;  exampleMMLFileStruct.noteCount = 1 |

This example data represents a MML file with the name “Test track”, which contains a single crochet of note “A”.

**catmidi – Procedural Abstraction**

The following is a flow chart showing a broad abstraction of how the catmidi program will work:

**F:\School work\A Level\Computer Science\MML-To-Midi-Project\Project Documentation\Diagrams\catmidi_procedural_abstraction.png**

**catmidi – Key Algorithms**

The catmidi program shares many of the same algorithms as the mmltomidi program, including the variable length quantity writing algorithm and the endianness swapper. In light of this, only algorithms, which aren’t featured in the mmltomidi program, are described in the following sections.

**Variable Length Quantity Reading**

One of the main algorithms used in the catmidi program is one that reads a variable length quantity and returns an integer. This is very similar to the variable length quantity writing algorithm covered before. It will take a pointer to the variable length quantity to be read as an input, and return an integer. The table below shows what outputs would be expected from the given inputs.

|  |  |
| --- | --- |
| Input Data | Number Outputted |
| 00 00 00 00 | 00 |
| 00 00 00 7F | 7F |
| 00 00 81 00 | 80 |
| 00 00 FF 7F | 3F FF |
| 00 81 80 00 | 40 00 |
| FF FF FF 7F | 0F FF FF FF |

An implementation of this algorithm in C-like pseudo-code is shown below.

|  |
| --- |
| int variableLengthQuantity(char \*inputPtr) {  int output = 0;  while (1) {  read byte from input  append first 7 bits from read byte to output  if read byte has bit 8 set {  continue;  }  break;  }  return output;  } |

**Read MIDI Event**

A core algorithm used is that which reads an event from an input MIDI file and outputs a structure containing the event and its delta time, with the channel number replaced where appropriate. It will take a pointer to the buffer where the MIDI data is stored, a pointer to a event structure, which is where the event will be stored, and a channel number. The algorithm is broadly demonstrated below in pseudo-code.

|  |
| --- |
| void readMTrkEvent(unsigned char \*inputPtr, struct mtrkEvent \*outputPtr, char channelNumber) {  outputPtr->deltaTime = readVariableLengthQuantity(inputPtr);    Copy event to outputPtr->event    Replace channel number in applicable events    outputPtr->length = length of event stored  } |

**Combine MIDI Files**

The main algorithm of the catmidi program is that which actually combines the MIDI files. It will take a pointer to an output buffer and pointers to MIDI files that have been read into memory. The pseudo-code for this algorithm is shown below.

|  |
| --- |
| int combineMIDIFiles(char \*outputBuffer, unsigned char \*inputBuffer[]) {  Write output chunk headers    Move the input buffer pointers to the start of events    Read an event from each MIDI file and store them  while (1) {  Write the event with the smallest delta time to the output    If this was the end of track MIDI event {  return length of written MIDI file;  }    Subtract delta time of event written from all other event delta times    Read the next event from the input buffer the event was written from  }  } |

**catmidi – Main Data Structures**

The only data structure in use in the catmidi program is that which stores the read MIDI events. It is shown below as a C structure.

struct mtrkEvent {

char event[262];

short length;

int deltaTime;

};

The event itself is stored in “event”, which is sized such that no recognised command will exceed its capacity. The length of the event is stored in “length”. Finally, the delta time of the MIDI event (that is, the time between carrying out the following command and the previous one), is stored in the “deltaTime” integer. In the MIDI file itself this is stored as a variable length quantity.

An example assignment of this structure is shown below.

|  |
| --- |
| struct mtrkEvent exampleEvent;  memcpy(exampleEvent.event, (char []) {0xFF, 0x2F, 0x00}, 3);  exampleEvent.length = 3;  exampleEvent.deltaTime = 0; |

**Music Macro Language Design**

This section describes the music macro language used by the mmltomidi program.

**Introduction**

The music macro language (MML) is a music description language that has been in use since 1978, although this was an early version. There has never been an official specification, so each implementation varies slightly, and over the years the language has evolved. The MML to MIDI converter uses a version of the MML derived largely from “Classical MML” with some “Modern MML” features present. Some new specific commands are included also, and some commands are changed where necessary.

All commands in this language have their own line and are terminated by a new line (“\n”, “\r “or “\r\n”).

**Comments**

Comments are started with two hash characters at the beginning of a new line . This makes the remainder of the line a comment; any more hashes found on the line have no effect. Two hashes are used because single hash starts a meta command.

**Playing Notes**

The “play” command is used to play a series of notes and macros. Spaces can be intermingled with the notes to improve the clarity of the code. An example usage of this command is shown below:

play c5e5g5

**Note Syntax**

Notes are written as the note name followed optionally by the length of the note as a digit – each value for this digit represents a musical note length, which can be seen in the table below. If a length is not given, the default value is used, which is initially 5, but can be changed with the “l” command detailed shortly. A rest is represented by the note name “r”. To play an accidental note a “+” or “-”, respectively, is added after the note name and before the note length. Accidentals applied to rests are ignored.

|  |  |  |
| --- | --- | --- |
| MML Note Value Number | Musical Note | |
| American Notation | Name |
| 0 | 1/32 | Demisemiquaver |
| 1 | 1/16 | Semiquaver |
| 2 | 1/16 + 1/32 | Dotted semiquaver |
| 3 | 1/8 | Quaver |
| 4 | 1/8 + 1/16 | Dotted quaver |
| 5 | 1/4 | Crochet |
| 6 | 1/4 + 1/8 | Dotted crochet |
| 7 | 1/2 | Minim |
| 8 | 1/2 + 1/4 | Dotted minim |
| 9 | 1 | Semibreve |

To alter how each note is played, there are some of commands entered with the notes. These are listed below (where square brackets and their contents are not literal):

* o[digit] Set the octave each following note is played in. The digit represents the scientific pitch notation (SPN) number of the desired octave. All notes entered before this command is entered are played in the 4th SPN octave (“A” will be 440 Hz.)
* < Shift the octave down by one.
* > Shift the octave up by one.
* v[digit] Set the volume of the following notes. By default, notes will play at 100% volume.
* p[number from 0 to 11] Transpose all the following notes up by the number following ‘p’ semitones. The default setting is 0.
* l[digit] Set the default length of the following notes to the digit. The initial default length is 5. Note that this does not affect the ‘v’ or ‘o’ commands.

In modern MML there is also a “t” command, which sets the tempo. This is not included, as a more obvious command on its own line is favoured for ease of reading.

**Meta Commands**

These commands are entered on their own lines only once and are all preceded by a single hash. They tell the converter how the rest of the file should be played and add information to the MIDI file.

* #tempo [BPM] – set the tempo in BPM of the track (where a beat is a crochet.) This should be set the same in each MML track file when combining them into one MIDI file. The default tempo is 120 BPM.
* #instrument [general MIDI patch number] – set the instrument the rest of the file should be played with. The default instrument is a piano (GM patch number 0.) This command is not present in other MML versions because it is only useful if the file is being converted to a MIDI file.
* #name [name] – set the name of the track. This is put verbatim into the MIDI file in a track name meta event, and can be very useful when altering the MIDI file directly. Only one instance of this command should be in a MML file, otherwise a syntax error will occur.

**Macros**

A macro in this version of MML is written as below (on it’s own line):

$c v9o4c5

The dollar sign shows that this is a macro definition, and the letter following this is the “name” of the macro. The text after the dollar sign and letter replaces any other instance of the macro name found. A limitation of this notation is that there are only 26 possible macro names, but it is done this way to be more compatible with other versions of MML. Macros can be defined more than once.

**Full Example**

To conclude the section, a short example MML file is shown below.

|  |
| --- |
| ##Example comment  #name test\_track  #instrument 0  #tempo 120  $c l3o4cdefgab>c  play v8$c |

This example plays the C major scale using quavers at a BPM of 120. The equivalent of this file in sheet music is shown below.



**MML in Regex and BNF**

This section shows how I will encode the language described in the previous section using regular expressions and Back-Naur form. These expressions can be put verbatim into the Lex and Yacc input files. The following table shows what regexes correspond to what BNF symbol, and gives a description on it.

|  |  |  |
| --- | --- | --- |
| Regex | BNF Symbol | Description |
| ^##.\*(\r|\n|(\r\n)) | COMMENT | Matches comment lines. |
| ^(\r|\n|(\r\n)) | LINE\_BREAK | Matches an empty line. |
| ^#tempo" "[0-9]{1,3}(\r|\n|(\r\n)) | TEMPO\_SET | Matches a tempo setting line. |
| ^#instrument" "[0-9]+(\r|\n|(\r\n)) | INSTRUMENT\_SET | Matches an instrument assigning line. |
| ^#name" "[a-zA-Z0-9\_]+(\r|\n|(\r\n)) | NAME\_SET | Matches a name setting line. |
| ^$[a-z]" "(([cdefgabrov][+-]?[0-9]?)|  ($[a-z])|[<>]|(p[0-9]+)|(l[0-9])|" ")+  (\r|\n|(\r\n)) | MACRO\_ASSIGNED | Matches a macro assignment. The middle portion is the regex that matches series of notes. |
| ^play" "(([cdefgabrov][+-]?[0-9]?)|  ($[a-z])|[<>]|(p[0-9]{1,2})|(l[0-9])|" ")+(\r|\n|(\r\n)) | PLAY\_COMMAND | Matches a play command. The middle portion is, again, the regex that matches a series of notes. |

The figure below contains the BNF grammer for the MML. “mmlFile” is the start symbol.

|  |
| --- |
| <mmlFile> ::= <line> | <mmlFile> <line>  <line> ::= <LINE\_BREAK> |  <COMMENT> |  <TEMPO\_SET> |  <INSTRUMENT\_SET> |  <NAME\_SET> |  <MACRO\_ASSIGNED> |  <PLAY\_COMMAND> |

**Technical Solution**

|  |
| --- |
| mmltomidi/makefile |
| BUILD\_DIR = ./build  STD = -std=c99  OPTI = -O3  EXE = mmltomidi  $(EXE)**:** main.c main.h y.tab.c lex.yy.c  gcc -g -w $(STD) $(OPTI) -o $(BUILD\_DIR)/$(EXE) main.c $(BUILD\_DIR)/lex.yy.c $(BUILD\_DIR)/y.tab.c    lex.yy.c**:** lex.l y.tab.h  lex -s -o $(BUILD\_DIR)/lex.yy.c lex.l    y.tab.c y.tab.h**:** yacc.y  yacc -d -o $(BUILD\_DIR)/y.tab.c yacc.y  .PHONY**:** clean  clean**:**  rm -f $(BUILD\_DIR)/$(EXE)  rm -f $(BUILD\_DIR)/**\***.o  rm -f $(BUILD\_DIR)/**\***.c  rm -f $(BUILD\_DIR)/**\***.h |

|  |
| --- |
| mmltomidi/main.c |
| #include <stdio.h>  #include <string.h>  #include <stdbool.h>  #include <unistd.h>  #include "main.h"  #include "mmlFileStruct.h"  **struct** mmlFileStruct processedMmlFile; //Necessary global to get information from lex.yy.c  **extern** FILE \*yyin; //For linking to lex.yy.c  **extern** bool macroEnabled[26]; //Necessary for clearing  **int** swapIntEndianness(**int** input) {  **int** output = 0;    **for** (**int** i = 0; i < 4; i++) {  \*((**char** \*) &output - i + 3) = \*((**char** \*) &input + i);  }    **return** output;  }  **int** swapShortEndianness(**short** input) {  **int** output = 0;    **for** (**int** i = 0; i < 2; i++) {  \*((**char** \*) &output - i + 1) = \*((**char** \*) &input + i);  }    **return** output;  }  **int** writeVariableLengthQuantity(**char** \*outputPtr, **int** input) {  **if** (input == 0) {  \*outputPtr = 0;  **return** 1;  }    **int** length = 5;    **for** (**int** i = 4; i >= 0; i--) {  **if** (input >> i \* 7) {  **break**;    } **else** {  length--;  }  }    **for** (**int** i = length - 1; i >= 0; i--) {  **if** (i != 0) {  \*(outputPtr + length - i - 1) = ((input >> i \* 7) & 0x7F) + 0x80;    } **else** {  \*(outputPtr + length - i - 1) = (input >> i \* 7) & 0x7F;  }  }    **return** length;  }  **void** writeMTrkHeader(**struct** mtrkHeader \*mtrkHeaderPtr, **int** trackLength) {  strncpy(mtrkHeaderPtr->chunkType, "MTrk", 4);  mtrkHeaderPtr->length = swapIntEndianness(trackLength);  }  **void** writeMThdHeader(**struct** mthdHeader \*mthdHeaderPtr) {  strncpy(mthdHeaderPtr->chunkType, "MThd", 4);  mthdHeaderPtr->length = swapIntEndianness(6);  mthdHeaderPtr->format = 0;  mthdHeaderPtr->ntrks = swapShortEndianness(1);  mthdHeaderPtr->division = swapShortEndianness(8);  }  **int** generateMIDIFile(**char** \*\*outputPtr, **struct** mmlFileStruct \*midiData) {  //Points outputPtr towards a malloc assigned array    \*outputPtr = malloc(65536);    **if** (\*outputPtr == NULL) {  fprintf(stderr, "Error - memory could not be assigned by malloc\n");  **return** NULL;  }    **struct** mthdHeader \*outputMThdHeader = \*outputPtr;  **struct** mtrkHeader \*outputMTrkHeader = \*outputPtr + 14;  **char** \*trackChunkPtr = \*outputPtr + 22;    writeMThdHeader(outputMThdHeader);    **if** (midiData->name[0]) {  memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0xff, 0x03, strlen(midiData->name)***}***, 4);  strcpy(trackChunkPtr += 4, midiData->name);  trackChunkPtr += strlen(midiData->name);  }    memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0xFF, 0x58, 0x04, 0x04, 0x02, 0x18, 0x08***}***, 8); //Time signature  trackChunkPtr += 8;    memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0xFF, 0x51, 0x03***}***, 4); //Tempo  \*((**int** \*) (trackChunkPtr += 4)) = swapIntEndianness(30000000 / 120) >> 8;  trackChunkPtr += 3;    memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0xC0, 0x00***}***, 3); //Default instrument  trackChunkPtr += 3;    **char** octave = 4;  **char** velocity = 0x7F;  **char** transposition = 0;  **char** noteLookup[7] = {21, 23, 12, 14, 16, 17, 19};  **char** deltaTimeLookup[10] = {1, 2, 3, 4, 6, 8, 12, 16, 24, 32};  **for** (**int** i = 0; i < midiData->noteCount; i++) {  **struct** note currentNote = midiData->notes[i];    **switch** (currentNote.command) {  **case** 'o':  octave = currentNote.modifier;  **break**;    **case** '<':  octave -= octave != 0;  **break**;    **case** '>':  octave += octave != 9;  **break**;    **case** 'p':  transposition = currentNote.modifier;  **break**;    **case** 'v':  velocity = (0x7F \* currentNote.modifier) / 9;  **break**;    **case** 't':  memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0xFF, 0x51, 0x03***}***, 4);  \*((**int** \*) (trackChunkPtr += 4)) = swapIntEndianness(30000000 / currentNote.modifier) >> 8;  trackChunkPtr += 3;    **break**;    **case** 'i':  memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0xC0, currentNote.modifier***}***, 3);  trackChunkPtr += 3;    **break**;    **default**:  ;  **char** noteNumber = noteLookup[currentNote.command - 'a'] + 12 \* octave + currentNote.accidental + transposition;    memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0x90, (currentNote.command != 'r') \* noteNumber, (currentNote.command != 'r') \* velocity***}***, 4);  trackChunkPtr += 4;    trackChunkPtr += writeVariableLengthQuantity(trackChunkPtr, deltaTimeLookup[currentNote.modifier]);  memcpy(trackChunkPtr, (**char** []) ***{***0x80, (currentNote.command != 'r') \* noteNumber, (currentNote.command != 'r') \* velocity***}***, 3);  trackChunkPtr += 3;    **break**;  }  }    memcpy(trackChunkPtr, (**char** []) ***{***0x00, 0xFF, 0x2F, 0x00***}***, 4);  trackChunkPtr += 4;    writeMTrkHeader(outputMTrkHeader, trackChunkPtr - \*outputPtr - 22);  \*outputPtr = realloc(\*outputPtr, trackChunkPtr - \*outputPtr + 1);  **if** (\*outputPtr == NULL) {  fprintf(stderr, "Error - malloc'd array could not be reallocated\n");    **return** NULL;  }    **return** trackChunkPtr - \*outputPtr;  }  bool fileReadable(**char** \*path) {  **if** (access(path, R\_OK)) {  fprintf(stderr, "File %s is not readable\n", path);  **return** false;  }    **return** true;  }  bool pathValid(**char** \*path) {  //Currently does not error on a directory  **if** (access(path, F\_OK)) {  fprintf(stderr, "File %s does not exist\n", path);  **return** false;  }    **return** true;  }  bool correctCallForm(**int** argc, **char** \*argv[]) {  **if** ((argc != 2) && (argc != 4)) {  fprintf(stderr, "Invalid number of arguments given\n");    **return** false;  }    **return** true;  }  **int** main(**int** argc, **char** \*argv[]) {  **if** (!correctCallForm(argc, argv)) {  fprintf(stderr, "Usage: mmltomidi [-o output\_path] file\n");    **return** 1;  }    bool outputPathGiven = !strcmp(argv[1], "-o");  **char** \*outputPath = (outputPathGiven) ? argv[2] : "output.midi";  **char** \*inputPath = (outputPathGiven) ? argv[3] : argv[1];  **if** ((!pathValid(inputPath)) || (!fileReadable(inputPath))) {  **return** 1;  }    memset(&processedMmlFile, 0, **sizeof**(processedMmlFile));  memset(macroEnabled, 0, 26);    yyin = fopen(inputPath, "rb");  **int** yyparseResult = yyparse();  fclose(yyin);    **if** (yyparseResult == 1) {  fprintf(stderr, "Syntax error encountered by parser - terminating\n");    **return** 1;  }    **char** \*midiBuffer;  **int** midiBufferLength = generateMIDIFile(&midiBuffer, &processedMmlFile);    **if** (midiBuffer == NULL) {  **return** 1;  }    FILE \*outputFile = fopen(outputPath, "wb");    **if** (outputFile == NULL) {  fprintf(stderr, "Output file could not be created/opened\n");    **return** 1;  }    fwrite(midiBuffer, 1, midiBufferLength, outputFile);    free(midiBuffer);  fclose(outputFile);  **return** 0;  } |

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| mmltomidi/main.h |
| #ifndef MAIN\_H  #define MAIN\_H  **extern** **int** yyparse (**void**); //Function prototype for linking to y.tab.c  **struct** mthdHeader {  **char** chunkType[4];  **int** length;  **short** format;  **short** ntrks;  **short** division;  };  **struct** mtrkHeader {  **char** chunkType[4];  **int** length;  };  #endif |

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| mmltomidi/lex.l |
| **%{**  #include <stdlib.h>  #include <string.h>  #include <stdbool.h>  #include "y.tab.h"  #include "../mmlFileStruct.h"  **extern** **struct** mmlFileStruct processedMmlFile;  **char** macroTable[26][256]; //Null terminated  bool macroEnabled[26];  **void** replaceSubstring(**char** \*source, **char** \*find, **char** \*replace) {  //Requires source to point to a malloc assigned array    **int** matches = 0;  **char** \*i = strstr(source, find);    **while** (i != NULL) {  matches++;  i = strstr(i + 1, find);  }    **if** (!matches) {  **return**;  }    **char** originalSource[strlen(source)];  strcpy(originalSource, source);    source = realloc(source, strlen(source) - matches \* strlen(find) + matches \* strlen(replace));    **int** sourceLen = strlen(source) - matches \* strlen(find) + matches \* strlen(replace);    **if** (source == NULL) {  **return**;  }    **int** oldIndex = 0, newIndex = 0;  **char** \*nextMatch = NULL;    **while** (oldIndex != strlen(originalSource)) {  **if** (nextMatch == NULL) {  nextMatch = strstr(originalSource + oldIndex, find);  **if** (nextMatch == NULL) {  strcpy(source + newIndex, originalSource + oldIndex);  **break**;  }  }    **if** (nextMatch == originalSource + oldIndex) {  strcpy(source + newIndex, replace);  newIndex += strlen(replace);  oldIndex += strlen(find);  nextMatch = NULL;    } **else** {  source[newIndex++] = originalSource[oldIndex++];  }  }  }  **%}**  **%%**  **^**##**.\*(\**r**|\**n**|(\**r**\**n**))** {  **return** COMMENT;  }  **^(\**r**|\**n**|(\**r**\**n**))** {  **return** LINE\_BREAK;  }    **^**#tempo" "**[**0**-**9**]**{1,3}**(\**r**|\**n**|(\**r**\**n**))** {  **int** tempoNumber = atoi(yytext + 7);    **if** (tempoNumber > 255) {  strcpy(yylval.errorMessage, "Error - tempo set higher than 255");  **return** ERROR;  }  processedMmlFile.notes[processedMmlFile.noteCount].command = 't';  processedMmlFile.notes[processedMmlFile.noteCount++].modifier = tempoNumber;  **return** TEMPO\_SET;  }    **^**#instrument" "**[**0**-**9**]+(\**r**|\**n**|(\**r**\**n**))** {  **int** instrumentNumber = atoi(yytext + 11);    **if** (instrumentNumber > 127) {  strcpy(yylval.errorMessage, "Error - instrument set higher than 127");  **return** ERROR;  }    processedMmlFile.notes[processedMmlFile.noteCount].command = 'i';  processedMmlFile.notes[processedMmlFile.noteCount++].modifier = instrumentNumber;  **return** INSTRUMENT\_SET;  }    **^**#name" "**[**a**-**zA**-**Z0**-**9\_**]+(\**r**|\**n**|(\**r**\**n**))** {  **static** bool nameSet = false;    **if** (nameSet) {  strcpy(yylval.errorMessage, "Error - name set more than once");  **return** ERROR;  }    nameSet = true;  **int** i = 5;    **while** (yytext[i] != '\n' && yytext[i] != '\r') {  **if** (i == 261) {  strcpy(yylval.errorMessage, "Error - name set was too long: limit is 255");  **return** ERROR;  }    processedMmlFile.name[i - 6] = yytext[i++];  }    processedMmlFile.name[i - 6] = '\0';  **return** NAME\_SET;  }    **^$[**a**-**z**]**" "**(([**cdefgabrov**][+-]?[**0**-**9**]?)|($[**a**-**z**])|[**<>**]|(**p**[**0**-**9**]+)|(**l**[**0**-**9**])|**" "**)+(\**r**|\**n**|(\**r**\**n**))** {  **int** i = 3;    **while** (yytext[i] != '\n' && yytext[i] != '\r') {  **if** (i == 258) {  strcpy(yylval.errorMessage, "Macro assigned was too long - limit is 255");  **return** ERROR;  }    macroTable[yytext[1] - 'a'][i - 3] = yytext[i++];  }    macroEnabled[yytext[1] - 'a'] = true;  macroTable[yytext[1] - 'a'][i - 3] = '\0';    **return** MACRO\_ASSIGNED;  }    **^**play" "**(([**cdefgabrov**][+-]?[**0**-**9**]?)|($[**a**-**z**])|[**<>**]|(**p**[**0**-**9**]**{1,2}**)|(**l**[**0**-**9**])|**" "**)+(\**r**|\**n**|(\**r**\**n**))** {  **char** \*processedYYText = malloc(strlen(yytext)); //Malloc required for replaceSubstring    **if** (processedYYText == NULL) {  strcpy(yylval.errorMessage, "Error - memory could not be malloc'd");  **return** ERROR;  }    strcpy(processedYYText, yytext);    **for** (**int** i = 0; i < strlen(yytext); i++) {  **if** ((yytext[i] == '$') && (!macroEnabled[yytext[i + 1] - 'a'])) {  strcpy(yylval.errorMessage, "Macro used but not assigned");  **return** ERROR;  }  }    **for** (**char** i = 0; i < 26; i++) {  **if** (macroEnabled[i]) {  replaceSubstring(processedYYText, (**char** []) {'$', i + 'a', 0x00}, macroTable[i]);    **if** (processedYYText == NULL) {  strcpy(yylval.errorMessage, "Error - memory assigned by malloc could not be reallocated");  **return** ERROR;  }  }  }    **int** index = 5;  **char** defaultLength = 5;    **while** (index < strlen(processedYYText)) {  **if** (strchr("cdefgabrov", processedYYText[index]) != NULL) {  processedMmlFile.notes[processedMmlFile.noteCount].command = processedYYText[index++];  processedMmlFile.notes[processedMmlFile.noteCount].accidental = 0;  processedMmlFile.notes[processedMmlFile.noteCount].modifier = defaultLength;    **while** (1) {  **if** ((index < strlen(processedYYText)) && (strchr("+-", processedYYText[index]) != NULL)) {  processedMmlFile.notes[processedMmlFile.noteCount].accidental = (processedYYText[index++] == '+') ? 1 : -1;    **continue**;  }    **if** ((index < strlen(processedYYText)) && (strchr("0123456789", processedYYText[index]) != NULL)) {  processedMmlFile.notes[processedMmlFile.noteCount].modifier = processedYYText[index++] - '0';    **continue**;  }    **break**;  }    processedMmlFile.noteCount++;    } **else** **if** (strchr("<>", processedYYText[index]) != NULL) {  processedMmlFile.notes[processedMmlFile.noteCount++].command = processedYYText[index++];    } **else** **if** (processedYYText[index] == 'p') {  processedMmlFile.notes[processedMmlFile.noteCount].command = processedYYText[index++];  processedMmlFile.notes[processedMmlFile.noteCount].modifier = 0;    **if** ((index + 1 < strlen(processedYYText)) && (strchr("0123456789", processedYYText[index + 1]) != NULL)) {  processedMmlFile.notes[processedMmlFile.noteCount].modifier = (processedYYText[index++] - '0') \* 10;  }    processedMmlFile.notes[processedMmlFile.noteCount].modifier += processedYYText[index++] - '0';    **if** (processedMmlFile.notes[processedMmlFile.noteCount++].modifier > 11) {  strcpy(yylval.errorMessage, "Transposition set too high - only values from 0 to 11 are valid");  **return** ERROR;  }    } **else** **if** (processedYYText[index] == 'l') {  defaultLength = processedYYText[++index] - '0';  index++;    } **else** {  index++;  }  }  free(processedYYText);  **return** PLAY\_COMMAND;  }    **.|\**n**|\**r {  **return** ERROR;  }  **%%** |

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| mmltomidi/mmlFileStruct.h |
| #ifndef MMLFILESTRUCT\_H  #define MMLFILESTRUCT\_H  //Necessary for only one copy of the struct definition  **struct** note {  **char** command;  **char** accidental; //-1 for flat, 1 for sharp  **unsigned** **char** modifier;  };  **struct** mmlFileStruct {  **char** name[256]; //Null terminated    **struct** note notes[16384];  **int** noteCount;  };  #endif |

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| mmltomidi/yacc.y |
| **%{**  #include <stdio.h>  #include <stdbool.h>  **void** yyerror(**char** \*s) {  fprintf(stderr, "%s\n", s);  }  **int** yywrap() {  **return** 1;  }  **%}**  **%union** {  **int** value;  **char** errorMessage[256];  **}**  **%start** mmlFile  **%token** <value> COMMENT  **%token** <value> LINE\_BREAK  **%token** <value> TEMPO\_SET  **%token** <value> INSTRUMENT\_SET  **%token** <value> NAME\_SET  **%token** <value> MACRO\_ASSIGNED  **%token** <value> PLAY\_COMMAND  **%token** <errorMessage> ERROR  **%type** <value> line  **%%**  **mmlFile**: **line**  | **mmlFile** **line**  ;  **line**: **LINE\_BREAK**  | **COMMENT**  | **TEMPO\_SET**  | **INSTRUMENT\_SET**  | **NAME\_SET**  | **MACRO\_ASSIGNED**  | **PLAY\_COMMAND**  | **ERROR** {  fprintf(stderr, "%s\n", $1);  YYERROR;  };  **%%** |

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| catmidi/main.c |
| #include <stdio.h>  #include <stdlib.h>  #include <stdbool.h>  #include <unistd.h>  #include <string.h>  #include "main.h"  **int** readVariableLengthQuantity(**char** \*inputPtr) {  **char** \*workingPtr = inputPtr;    **while** (\*workingPtr & 0x80) {  workingPtr++;  }    **int** output = 0;  **int** outputShift = 0;  **do** {  output |= (\*workingPtr & 0x7F) << outputShift;    outputShift += 7;    } **while** (workingPtr-- != inputPtr);  **return** output;  }  **int** writeVariableLengthQuantity(**char** \*outputPtr, **int** input) {  **if** (input == 0) {  \*outputPtr = 0;  **return** 1;  }    **int** length = 5;    **for** (**int** i = 4; i >= 0; i--) {  **if** (input >> i \* 7) {  **break**;    } **else** {  length--;  }  }    **for** (**int** i = length - 1; i >= 0; i--) {  **if** (i != 0) {  \*(outputPtr + length - i - 1) = ((input >> i \* 7) & 0x7F) + 0x80;    } **else** {  \*(outputPtr + length - i - 1) = (input >> i \* 7) & 0x7F;  }  }    **return** length;  }  **char** readMTrkEvent(**unsigned** **char** \*\*inputPP, **struct** mtrkEvent \*outputPtr, **char** channelNumber) {  outputPtr->deltaTime = readVariableLengthQuantity(\*inputPP);    Read event into outputPtr    Replace channel number in appropriate commands    outputPtr->length = length of event stored  }  **char** readMTrkEvent(**unsigned** **char** \*\*inputPP, **struct** mtrkEvent \*outputPtr, **char** channelNumber) {  //Returns non-zero on error    outputPtr->deltaTime = readVariableLengthQuantity((**char** \*) \*inputPP);  **while** (\*\*inputPP & 0x80) {  (\*inputPP)++;  }    (\*inputPP)++;    **unsigned** **char** \*originalPtr = \*inputPP;  **switch** (\*\*inputPP) {  **case** 0xFF:  (\*inputPP)++;    **switch** (\*\*inputPP) {  **case** 0x03: //Name  (\*inputPP)++;  \*inputPP += \*\*inputPP + 1;    **break**;    **case** 0x2f: //End  \*inputPP += 2;    **break**;    **case** 0x51: //Tempo  \*inputPP += 5;    **break**;    **case** 0x58: //Time sig.  \*inputPP += 6;    **break**;    **default**:  fprintf(stderr, "Unknown MTrk event encountered\n");    **return** 1;  }    **break**;    **case** 0x80: //Note off  **case** 0x90: //Note on  \*\*inputPP |= channelNumber;  \*inputPP += 3;    **break**;    **case** 0xC0: //Patch change  \*\*inputPP |= channelNumber;  \*inputPP += 2;    **break**;    **default**:  fprintf(stderr, "Unknown MTrk event encountered\n");    **return** 1;  }  outputPtr->length = \*inputPP - originalPtr;  memcpy(outputPtr->event, originalPtr, outputPtr->length);    **return** 0;  }  **int** swapIntEndianness(**int** input) {  **int** output = 0;    **for** (**int** i = 0; i < **sizeof**(**int**); i++) {  \*((**char** \*) &output + **sizeof**(**int**) - i - 1) = \*((**char** \*) &input + i);  }    **return** output;  }  **int** swapShortEndianness(**short** input) {  **int** output = 0;    **for** (**int** i = 0; i < **sizeof**(**short**); i++) {  \*((**char** \*) &output + **sizeof**(**short**) - i - 1) = \*((**char** \*) &input + i);  }    **return** output;  }  **void** writeMTrkHeader(**struct** mtrkHeader \*mtrkHeaderPtr, **int** trackLength) {  strncpy(mtrkHeaderPtr->chunkType, "MTrk", 4);  mtrkHeaderPtr->length = swapIntEndianness(trackLength);  }  **void** writeMThdHeader(**struct** mthdHeader \*mthdHeaderPtr) {  strncpy(mthdHeaderPtr->chunkType, "MThd", 4);  mthdHeaderPtr->length = swapIntEndianness(6);  mthdHeaderPtr->format = 0;  mthdHeaderPtr->ntrks = swapShortEndianness(1);  mthdHeaderPtr->division = swapShortEndianness(8);  }  **int** combineMIDIFiles(**char** \*outputBuffer, **unsigned** **char** \*inputBuffer[], **char** inputBufferCount) {  //Returns zero on error    **struct** mthdHeader \*outputMThdHeader = (**void** \*) outputBuffer;  **struct** mtrkHeader \*outputMTrkHeader = (**void** \*) outputBuffer + 14;  **char** \*trackPtr = (**void** \*) outputBuffer + 22;    writeMThdHeader(outputMThdHeader);    **unsigned** **char** \*inputBufferPtr[inputBufferCount];  **struct** mtrkEvent inputEvent[inputBufferCount];    **for** (**int** i = 0; i < inputBufferCount; i++) {  inputBufferPtr[i] = inputBuffer[i] + 22;    **if** (readMTrkEvent(&inputBufferPtr[i], &inputEvent[i], i)) {  **return** 0;  }  }    bool nameSet = false;  bool timeSignatureSet = false;    **int** smallestDeltaTime;  **char** soonestEventIndex;  **struct** mtrkEvent \*soonestEvent;    **while** (1) {  smallestDeltaTime = inputEvent[0].deltaTime;  soonestEventIndex = 0;    **for** (**int** i = 1; i < inputBufferCount; i++) {  **if** (inputEvent[i].deltaTime < smallestDeltaTime) {  smallestDeltaTime = inputEvent[i].deltaTime;  soonestEventIndex = i;  }  }    **for** (**int** i = 0; i < inputBufferCount; i++) {  **if** (i == soonestEventIndex) {  **continue**;  }    inputEvent[i].deltaTime -= smallestDeltaTime;  }    soonestEvent = &inputEvent[soonestEventIndex];    **if** (!memcmp(soonestEvent->event, (**char** []) ***{***0xFF, 0x03***}***, 2)) { //Name setting event  **if** (nameSet) {  **if** (readMTrkEvent(&inputBufferPtr[soonestEventIndex], &inputEvent[soonestEventIndex], soonestEventIndex)) {  **return** 0;  }    **continue**;  }  nameSet = true;  }    **if** (!memcmp(soonestEvent->event, (**char** []) ***{***0xFF, 0x58, 0x04***}***, 3)) { //Time signature setting event  **if** (timeSignatureSet) {  **if** (readMTrkEvent(&inputBufferPtr[soonestEventIndex], &inputEvent[soonestEventIndex], soonestEventIndex)) {  **return** 0;  }    **continue**;  }    timeSignatureSet = true;  }    trackPtr += writeVariableLengthQuantity(trackPtr, soonestEvent->deltaTime);  memcpy(trackPtr, soonestEvent->event, soonestEvent->length);  trackPtr += soonestEvent->length;    **if** (memcmp(soonestEvent->event, (**char** []) ***{***0xFF, 0x2F, 0x00***}***, 3) == 0) { //End of track event  **break**;  }    **if** (readMTrkEvent(&inputBufferPtr[soonestEventIndex], &inputEvent[soonestEventIndex], soonestEventIndex)) {  **return** 0;  }  }    writeMTrkHeader(outputMTrkHeader, trackPtr - outputBuffer - 22);    **return** trackPtr - outputBuffer;  }  **int** loadFile(**char** \*path, **unsigned** **char** \*\*buffer) {  FILE \*f = fopen(path, "rb");    fseek(f, 0, SEEK\_END);  **int** length = ftell(f);  rewind(f);    \*buffer = malloc(length);  fread(\*buffer, 1, length, f);    fclose(f);    **return** length;  }  bool fileReadable(**char** \*path) {  **if** (access(path, R\_OK)) {  fprintf(stderr, "File %s is not readable\n", path);  **return** false;  }    **return** true;  }  bool pathValid(**char** \*path) {  //Currently does not error on a directory  **if** (access(path, F\_OK)) {  fprintf(stderr, "File %s does not exist\n", path);  **return** false;  }    **return** true;  }  bool correctCallForm(**int** argc, **char** \*argv[]) {  **if** (argc < 2) {  fprintf(stderr, "Too few arguments supplied\n");    **return** false;  }    **if** (argc > 19) {  fprintf(stderr, "Too many arguments supplied - 16 files can be combined at most\n");    **return** false;  }    **return** true;  }  **int** main(**int** argc, **char** \*argv[]) {  **if** (!correctCallForm(argc, argv)) {  fprintf(stderr, "Usage: catmidi [-o output\_path] [path ...]\n");    **return** 1;  }  bool outputPathGiven = !strcmp(argv[1], "-o");  **char** startOfInputs = (outputPathGiven) ? 3 : 1;  **char** numberOfInputs = argc - startOfInputs;  **for** (**int** i = startOfInputs; i < argc; i++) {  **if** ((!pathValid(argv[i])) || (!fileReadable(argv[i]))) {  **return** 1;  }  }    **char** outputBuffer[65536];  **unsigned** **char** \*inputBuffer[numberOfInputs];    **for** (**int** i = 0; i < numberOfInputs; i++) {  loadFile(argv[i + startOfInputs], &inputBuffer[i]);  }    **int** outputBufferLength = combineMIDIFiles(outputBuffer, inputBuffer, numberOfInputs);    **for** (**int** i = 0; i < numberOfInputs; i++) {  free(inputBuffer[i]);  }    **if** (outputBufferLength == 0) {  **return** 1;  }    FILE \*outputFile = fopen((outputPathGiven) ? argv[2] : "./output.midi", "wb");    **if** (outputFile == NULL) {  fprintf(stderr, "Output file could not be created\n");    **return** 1;  }    fwrite(outputBuffer, 1, outputBufferLength, outputFile);  fflush(outputFile);  fclose(outputFile);  **return** 0;  } |

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| catmidi/main.h |
| #ifndef MAIN\_H  #define MAIN\_H  **struct** mthdHeader {  **char** chunkType[4];  **int** length;  **short** format;  **short** ntrks;  **short** division;  };  **struct** mtrkHeader {  **char** chunkType[4];  **int** length;  };  **struct** mtrkEvent {  **char** event[259];  **short** length;  **int** deltaTime;  };  #endif |

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| catmidi/makefile |
| BUILD\_DIR = ./build  STD = -std=c99  OPTI = -O3  EXE = catmidi  $(EXE)**:** main.o  gcc -g -w $(STD) $(OPTI) -o $(BUILD\_DIR)/$(EXE) $(BUILD\_DIR)/main.o    main.o**:** main.c  gcc -c $(STD) $(OPTI) -o $(BUILD\_DIR)/main.o main.c  .PHONY**:** clean  clean**:**  rm -f $(BUILD\_DIR)/$(EXE)  rm -f $(BUILD\_DIR)/**\***.o |

**Testing**

When I started the project, I planned to use unit testing, and perform test driven development; due to the project making heavy use of the compiler compilers lex and yacc, however, I could not come up with a good way of performing unit testing on my programs. In light of this, I’ve decided to carry out testing of key functions in isolated source files with tailored test cases. The testing of the lexing and parsing elements of the programs will be done via white box testing.

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| Function prototype | **int** swapIntEndianness(**int** input) |
| Purpose | Swap the endianness of the integer “input” and return it. |
| Testing code | #include <stdio.h>  **struct** testCase {  **int** input;  **int** expectedOutput;  };  **int** swapIntEndianness(**int** input) {  **int** output = 0;    **for** (**int** i = 0; i < 4; i++) {  \*((**char** \*) &output - i + 3) = \*((**char** \*) &input + i);  }    **return** output;  }  **int** main(**int** argc, **char** \*argv[]) {  **struct** testCase tests[] = {{0x00000000, 0x00000000},  {0x000000FF, 0xFF000000},  {0x0000FF00, 0x00FF0000},  {0x00FF0000, 0x0000FF00},  {0xFF000000, 0x000000FF},  {0x12345678, 0x78563412}};    **int** actualOutput;    printf("Input Expected Actual \n");    **for** (**int** i = 0; i < **sizeof**(tests) / **sizeof**(**struct** testCase); i++) {  actualOutput = swapIntEndianness(tests[i].input);    printf("%08X %08X %08X", tests[i].input, tests[i].expectedOutput, actualOutput);    **if** (actualOutput != tests[i].expectedOutput) {  printf(" FAIL\n");    **continue**;  }    printf(" PASS\n");  }    **return** 0;  } |
| Outcome | C:\Users\Andy\AppData\Local\Microsoft\Windows\INetCache\Content.Word\a.png |

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| Function prototype | **int** writeVariableLengthQuantity(**char** \*outputPtr, **int** input) |
| Purpose | Write the integer “input” as a big endian variable length quantity at the pointer “outputPtr”. Return the length of the variable length quantity written. |
| Testing code | #include <stdio.h>  **struct** testCase {  **int** input;  **int** expectedVLQ;  **int** expectedReturn;  };  **int** writeVariableLengthQuantity(**char** \*outputPtr, **int** input) {  **if** (input == 0) {  \*outputPtr = 0;  **return** 1;  }    **int** length = 5;    **for** (**int** i = 4; i >= 0; i--) {  **if** (input >> i \* 7) {  **break**;    } **else** {  length--;  }  }    **for** (**int** i = length - 1; i >= 0; i--) {  **if** (i != 0) {  \*(outputPtr + length - i - 1) = ((input >> i \* 7) & 0x7F) + 0x80;    } **else** {  \*(outputPtr + length - i - 1) = (input >> i \* 7) & 0x7F;  }  }    **return** length;  }  **int** main(**int** argc, **char** \*argv[]) {  **struct** testCase tests[] = {{0x00000000, 0x00000000, 0},  {0x00000040, 0x00000040, 1},  {0x0000007F, 0x0000007F, 1},  {0x00000080, 0x00000081, 2},  {0x00002000, 0x000000C0, 2},  {0x00003FFF, 0x00007FFF, 2},  {0x00004000, 0x00008081, 3},  {0x00100000, 0x000080C0, 3},  {0x001FFFFF, 0x007FFFFF, 3},  {0x00200000, 0x00808081, 4},  {0x08000000, 0x008080C0, 4},  {0x0FFFFFFF, 0x7FFFFFFF, 4}};    **int** actualVLQ;  **int** actualReturn;    printf("Input Expected Expected Actual Actual \n");  printf(" VLQ Return VLQ Return \n");    **for** (**int** i = 0; i < **sizeof**(tests) / **sizeof**(**struct** testCase); i++) {  actualVLQ = 0;  actualReturn = writeVariableLengthQuantity((**char** \*) &actualVLQ, tests[i].input);    printf("%08X %08X %08X %08X %08X", tests[i].input, tests[i].expectedVLQ, tests[i].expectedReturn, actualVLQ, actualReturn);    **if** (actualVLQ != tests[i].expectedVLQ) {  printf(" FAIL\n");    **continue**;  }    printf(" PASS\n");  }    printf("\nNOTE: All VLQ values corrected for endianness\n");    **return** 0;  } |
| Outcome | C:\Users\Andy\AppData\Local\Microsoft\Windows\INetCache\Content.Word\a.png |

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| Function prototype | **int** readVariableLengthQuantity(**char** \*inputPtr) |
| Purpose | Read a big endian variable length quantity from pointer “inputPtr”, and return it as a little endian integer. |
| Testing code | #include <stdio.h>  **struct** testCase {  **char** input[4];  **int** expectedOutput;  };  **int** readVariableLengthQuantity(**char** \*inputPtr) {  **char** \*workingPtr = inputPtr;    **while** (\*workingPtr & 0x80) {  workingPtr++;  }    **int** output = 0;  **int** outputShift = 0;  **do** {  output |= (\*workingPtr & 0x7F) << outputShift;    outputShift += 7;    } **while** (workingPtr-- != inputPtr);  **return** output;  }  **int** main(**int** argc, **char** \*argv[]) {  **struct** testCase tests[] = {{{0x00, 0x00, 0x00, 0x00}, 0},  {{0x40, 0x00, 0x00, 0x00}, 0x40},  {{0x7F, 0x00, 0x00, 0x00}, 0x7F},  {{0x81, 0x00, 0x00, 0x00}, 0x80},  {{0xC0, 0x00, 0x00, 0x00}, 0x2000},  {{0xFF, 0x7F, 0x00, 0x00}, 0x3FFF},  {{0x81, 0x80, 0x00, 0x00}, 0x4000},  {{0xC0, 0x80, 0x00, 0x00}, 0x100000},  {{0xFF, 0xFF, 0x7F, 0x00}, 0x1FFFFF},  {{0x81, 0x80, 0x80, 0x00}, 0x200000},  {{0xC0, 0x80, 0x80, 0x00}, 0x8000000},  {{0xFF, 0xFF, 0xFF, 0x7F}, 0xFFFFFFF}};    **int** actualOutput;    printf("Input Expected Actual \n");    **for** (**int** i = 0; i < **sizeof**(tests) / **sizeof**(**struct** testCase); i++) {  actualOutput = readVariableLengthQuantity(tests[i].input);    **for** (**char** c = 0; c < 4; c++) {  printf("%02X", (**unsigned** **char**) tests[i].input[c]);  }    printf(" %08X %08X", tests[i].expectedOutput, actualOutput);    **if** (actualOutput != tests[i].expectedOutput) {  printf(" FAIL\n");    **continue**;  }    printf(" PASS\n");  }    **return** 0;  } |
| Outcome | C:\Users\Andy\AppData\Local\Microsoft\Windows\INetCache\Content.Word\a.png |

**Evaluation**

**Completion of the Objectives**

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| Objective | Evaluation |
| A program should be written that takes text file containing a variant of the MML as an input, and outputs a single-channel MIDI file that can be play with conventional software. | I completed this objective through the writing of the mmltomidi program. |
| A program should be written that takes multiple MIDI files generated by the aforementioned program and combines them into a single multi-channel MIDI file. This combined MIDI file should be playable using conventional software also. | I completed this objective with the writing of the catmidi program. |
| The programs written for this project should:   * Complete their execution in under one second, so as to not interrupt the users work flow * Use less than half a megabyte of memory during execution * Be a less than a quarter of a megabyte in size | I met all of these objectives:   * Both programs complete their execution in well under one second, even when compiled without any optimisation. * While it depends on the size of the files given as inputs to the programs, both programs generally use well under 512 kilobytes of memory. * Combined, the programs take up less than 60 kilobytes of disk spaces |
| A version of the music macro language should be designed that will be used as the input for the program that generates a single-channel MIDI file from a single MML file. This language should:   * Have all the functionality of existing variants of the MML, including support for:   + Octave changing   + Accidentals   + Default length setting   + Volume changing   + Tempo setting   + Macros * Have as unambiguous a syntax as possible, with a clear logical progression | I completed this objective in my design section. The language I designed there exceeds the functionality of most MML versions with the inclusion of transposition. It also is necessarily unambiguous as a BNF grammar had to be written for it. |

**Evaluation of Development**

I believe that the development of the project went well – the use of Lex, Yacc and makefiles all proved to be good decisions, as each saved me a great deal of time. An area that was notably lacking during development however was testing. I feel that I could have done more during the writing of my code.

Also, it would have been very useful to have a proper debugging facility during development, as I am confident this would have saved time.

**What I Would Change**

If I were to do the project again I would implement a better system for testing my programs, though I am still unsure of how this would be achieved. I would also consider the idea of developing a single program to solve the problem, as having two programs to use has proved to be tedious at times. Finally, I would like to add more functionality to the music description language designed for the project, and perhaps make it more similar to a programming language: this could be achieved with the inclusion of loops, variables and control structures.

**Bibliography**

The MIDI Manufacturers Association. “*The Complete MIDI 1.0 Detailed Specification*” (2013)

John R. Levine, Tony Mason & Doug Brown. “lex & yacc” (1995)